**R&D Insights from the Digital Testbed Air Cargo (DTAC)** 

# Autonomous Handling from Truck to Belly

Manuel Wehner • IATA Cargo Experts Conference (CEC) Brussels Airport • 25 September 2025





Sponsored b



Federal Ministry for Digitalization and Government Modernization

# Pitch topics



- ➤ AMR\* development for autonomous end-toend airport cargo handling
- Fleet monitoring and AMR control through state-of-the-art software
- Simulation and sensor tests for specific and neuralgic airport traffic situations

\* AMR = Autonomous Mobile Robot

















### Fraunhofer IML - R&D focus topics



Unrestricted





#### Current challenges in the air cargo industry:

### DTAC research focus (2021 – 2026)

Focus today – our robotic tests in 2024:



HOW can next-gen AMRs\* support Air Cargo Handling?

\* AMR: Autonomous Mobile Robot



Autonomous
Warehouse Handling &
Apron Transports



Our approach: R&D with own and market solutions

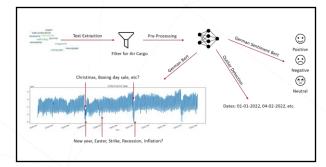
DTAC focus on AI:



HOW can AI improve Air Cargo efficiency?



Predictive Analytics



Our approach: analyses based on historic cargo data

DTAC focus on data:



Why is Data Sharing still so difficult?



Data Platform & Digital Avatar



Our approach: open-source server NE:ONE and IoT

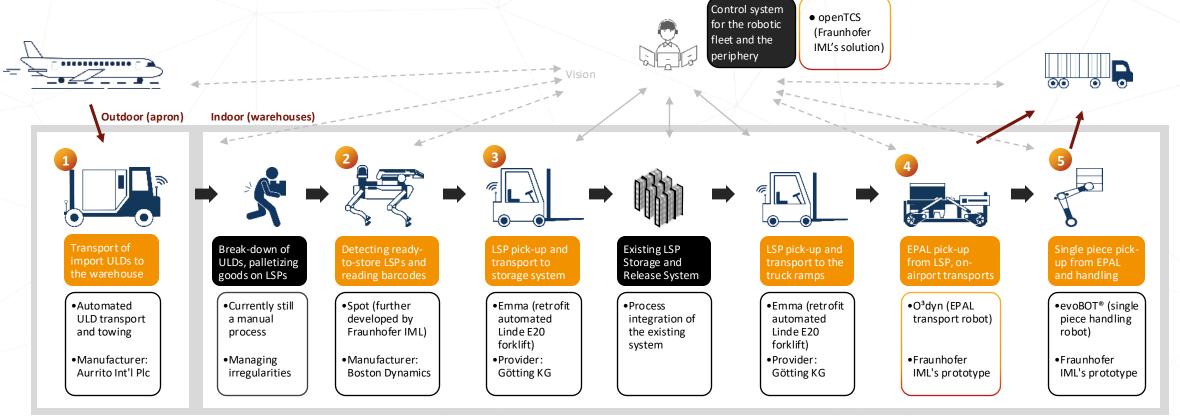




2024 - 3-month trials at MUC and STR with 5 different robots:

### Multi-robot testbed for cargo flow automation





**ULD**: Unit load device (air cargo containers / build-up units, various sizes)

**LSP**: Large metal storage pallet (130 x 130 cm or 200 x 200 cm)

**EPAL**: Standardized wooden Euro-pallet (120 x 80 cm)





#### 2 airports, 5 robots, 12 test weeks, 674 tests, 84% success rate

#### 2024 test results



















**Auto-DollyTug**® (Aurrigo)

Tests: n = 178

Success rate: 65 %

Autonomy level: 30 %



Outdoor functionality



Load handling

**Spot**<sup>®</sup> (Boston Dynamics & IML)

Tests: n = 77

Success rate: 95 %

Autonomy level: 60 %



Autonomy level



Assessing obstacles

LindeE20 (Götting KG)

Tests: n = 202

Success rate: 86 %

Autonomy level: 20 %



Repetit. storage tasks



**Unbalanced loads** 

O<sup>3</sup>dyn (Fraunhofer IML)

Tests: n = 146

Success rate: 97 %

Autonomy level: 20 %



Pick-up from pallet



**Busy intersections** 

**evoBOT**<sup>®</sup> (Fraunhofer IML)

Tests: n = 71

Success rate: 89 %

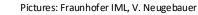
Autonomy level: 0 %



Different shapes



Automation outside lab







25.09.2025

13

#### Awards and nominations





1st place: "Air Cargo Sustainability Award"

"Start-Up and Small Business" category, The International Air Cargo Association (TIACA)

TIACA Exec. Summit 2025. Hongkong, 25 June 2025







**Highly Acclaimed: "International** Award for Excellence in Air Cargo"

"Innovative Logistics Solutions in Air Cargo" category, STAT Times

air cargo africa, Nairobi, 20. February 2025







**Top 5: "Air Cargo Technology Solution** Provider of the Year"

"Air Cargo Technology Solution Provider of the Year" category, Air Cargo Week (ACW)

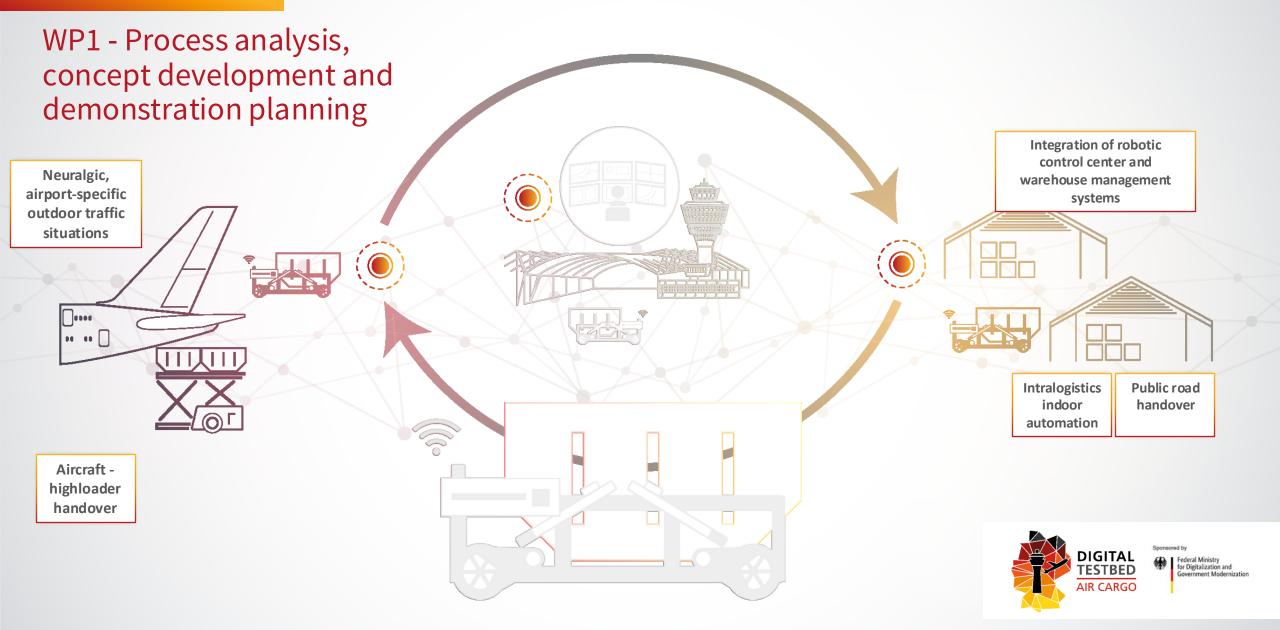
transport logistic, Munich, 03 June 25

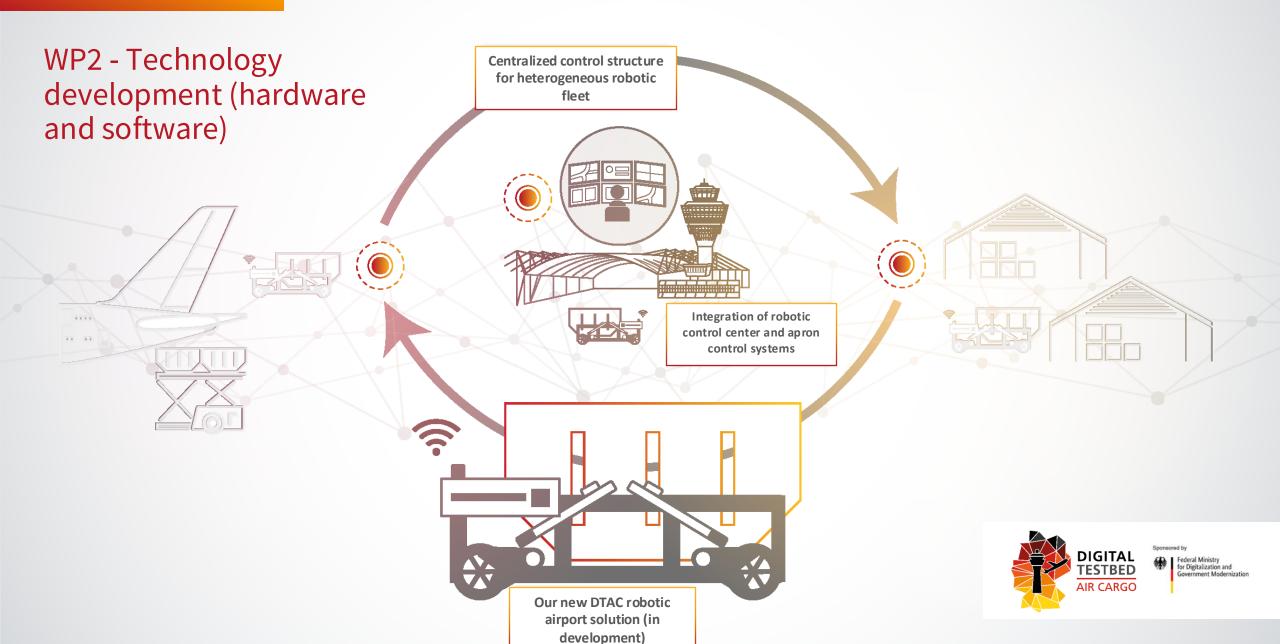






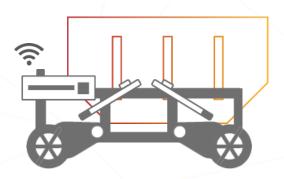
#### DTAC 2024 - 2026





# Vehicle requirements (selection)





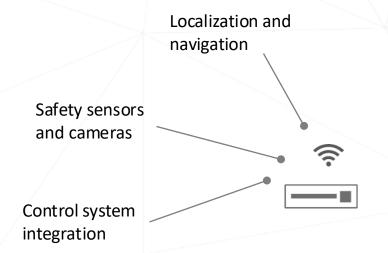




## Vehicle requirements (selection)

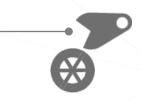
→ Rolling Chassis to be developed until 04/2026





Flexible load handling **Energy supply** and storage

Dynamic and omnidirectional maneuvering



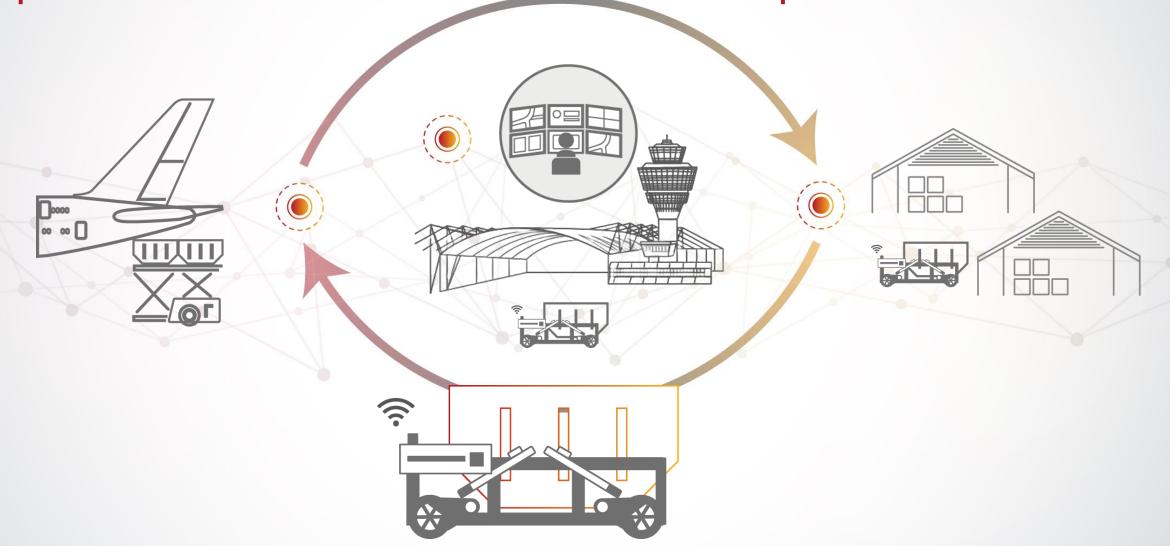






Centralizing monitoring and control:

openTCS functions as the heart of the operations



#### Centralizing monitoring and control:

### openTCS functions as the heart of the operations



- Open-source
- Manufacturer independent
- VDA5050 communication standard
- Airport specific control center for DTAC
- Web-based, mobile devices
- Integration with airport AI/Flightradar
- → Control system software for trials and implementations

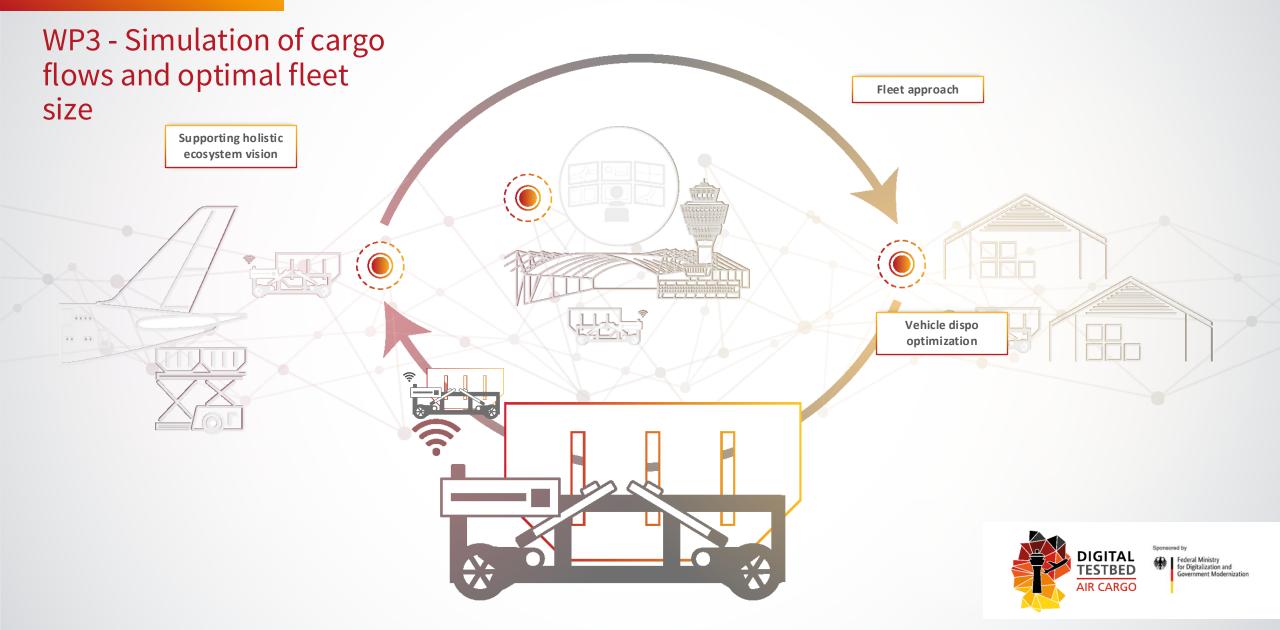






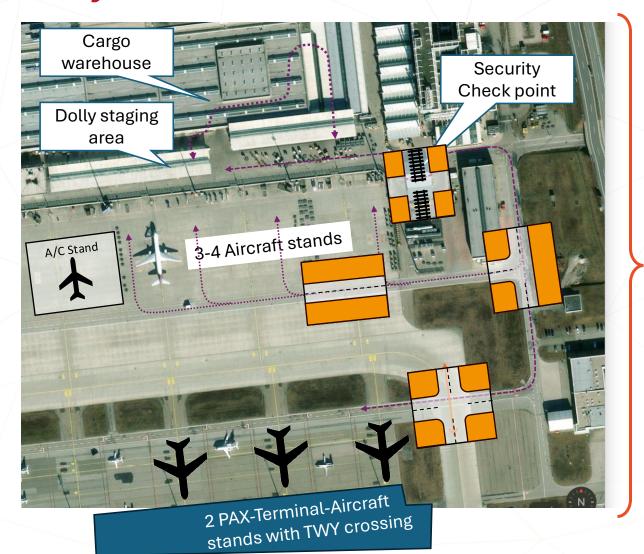


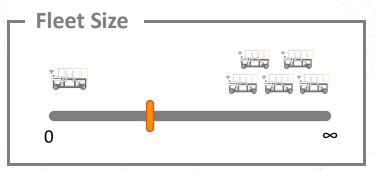
#### DTAC 2024 - 2026

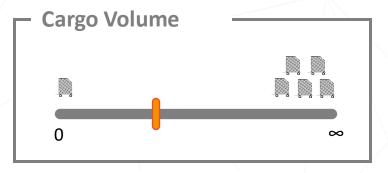


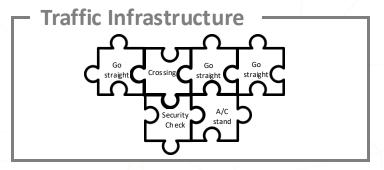
#### Modular simulation concept:

### Analysis of different fleet scenarios















"The control of airport surface traffic today can be described as manual.

(...) Many of the tasks [could] be done more easily, more reliably, and more efficiently with automation.

(...) A new [airport] surface surveillance and communication system <u>must be developed</u> to (...) <u>provide surveillance and classification</u> of surface vehicles."

Hollister, W. M., "Airport Surface Traffic Automation Study" Massachusetts Inst. of Tech., Technical Report ADA194553, ATC-156, DOT/FAA/PS-87/1, 1988.

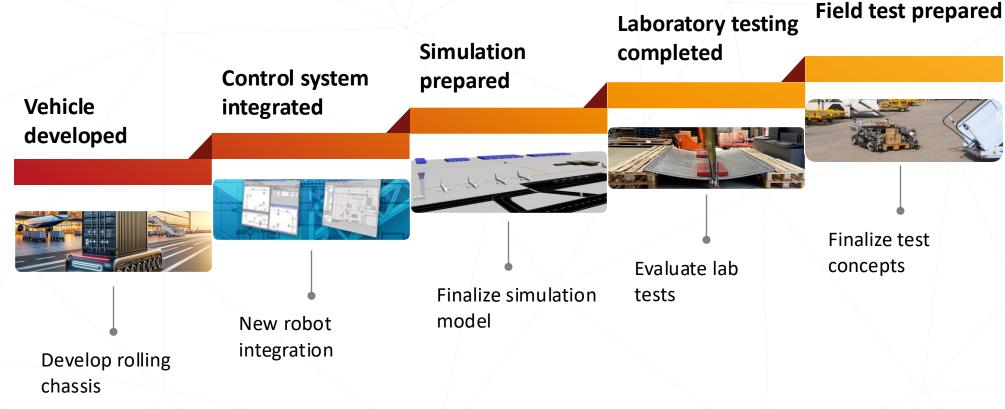
Has the time finally come?





### Next steps – outlook until 08/2026







Target: new vehicle ready for airport tests from 09/2026





#### Thank you for your participation!

Contact details:

Manuel Wehner, M.Sc.

Fraunhofer IML - Aviation Logistics



**Tel.** +49 (0)69 668118-359

**Email** manuel.wehner@iml.fraunhofer.de





